DGC-2020ES

Digital Genset Controller

Accessories Instruction Manual

12570 Route 143 • Highland, Illinois 62249-1074 USA
Tel +1 618.654.2341 • Fax +1 618.654.2351
www.basler.com • info@basler.com

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⚠ **WARNING:** California's Proposition 65 requires special warnings for products that may contain chemicals known to the state of California to cause cancer, birth defects, or other reproductive harm. Please note that by posting this Proposition 65 warning, we are notifying you that one or more of the Proposition 65 listed chemicals may be present in products we sell to you. For more information about the specific chemicals found in this product, please visit https://www.basler.com/Prop65.

Preface

This instruction manual provides information about the accessories for the DGC-2020ES Digital Genset Controller. To accomplish this, the following information is provided:

- CEM-2020 (Contact Expansion Module)

Conventions Used in this Manual

Important safety and procedural information is emphasized and presented in this manual through Warning, Caution, and Note boxes. Each type is illustrated and defined as follows.

Warning!

Warning boxes call attention to conditions or actions that may cause personal injury or death.

Caution

Caution boxes call attention to operating conditions that may lead to equipment or property damage.

Note

Note boxes emphasize important information pertaining to Digital Genset Controller installation or operation.

DGC-2020ES Instruction Manual Catalog

Available instruction manuals for the DGC-2020ES are listed in Table 1.

Table 1. Instruction Manuals

Part Number	Description
9469200993	Quick Start
9469200994	Installation
9469200995	Configuration
9469200996	Operation
9469200997	Accessories (this manual)

Basler Electric
12570 State Route 143
Highland IL 62249-1074 USA
www.basler.com
info@basler.com
Tel: +1 618.654.2341
Fax: +1 618.654.2351

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Warning!

READ THIS MANUAL. Read this manual before installing, operating, or maintaining the DGC-2020ES. Note all warnings, cautions, and notes in this manual as well as on the product. Keep this manual with the product for reference. Only qualified personnel should install, operate, or service this system. Failure to follow warning and cautionary labels may result in personal injury or property damage. Exercise caution at all times.

Caution

Installing previous versions of firmware may result in compatibility issues causing the inability to operate properly and may not have the enhancements and resolutions to issues that more recent versions provide. Basler Electric highly recommends using the latest version of firmware at all times. Using previous versions of firmware is at the user's risk and may void the warranty of the unit.

Basler Electric does not assume any responsibility to compliance or noncompliance with national code, local code, or any other applicable code. This manual serves as reference material that must be well understood prior to installation, operation, or maintenance.

For terms of service relating to this product and software, see the *Commercial Terms of Products and Services* document available at www.basler.com/terms.

This publication contains confidential information of Basler Electric Company, an Illinois corporation. It is loaned for confidential use, subject to return on request, and with the mutual understanding that it will not be used in any manner detrimental to the interests of Basler Electric Company and used strictly for the purpose intended.

It is not the intention of this manual to cover all details and variations in equipment, nor does this manual provide data for every possible contingency regarding installation or operation. The availability and design of all features and options are subject to modification without notice. Over time, improvements and revisions may be made to this publication. Before performing any of the following procedures, contact Basler Electric for the latest revision of this manual.

The English-language version of this manual serves as the only approved manual version.

Revision History

A historical summary of the changes made to this instruction manual is provided below. Revisions are listed in reverse chronological order.

Visit www.basler.com to download the latest hardware, firmware, and BESTCOMS*Plus*® revision histories.

Instruction Manual Revision History

Manual Revision and Date	Change
G, Jan-25	• Updated the China RoHS table for the CEM-2020
F, Sep-24	• Added FCC requirements • Removed EAC mark • Added note about vibration on connector plugs
E, Jul-23	• Added China RoHS for the CEM-2020 • Minor text edits throughout manual
D, Dec-21	• Added ABS maritime certification and UKCA compliance • Removed CEM-2020 CSA certification
C, Jul-21	• Removed CEM-2020 UL Recognition for use in Hazardous Locations • Minor text edits
B, Nov-19	• Removed Rev Letter from all pages. • Changed sequential numbering to sectional numbering. • Moved Instruction Manual Revision History into *Preface*. • Removed standalone Revision History chapter.
A1, Apr-19	• Updated Proposition 65 statement
A, Sep-18	• Updated output contacts ratings and added hazardous location specs in the *CEM-2020* chapter • Updated *Revision History* chapter
—, Apr-17	• Initial release

Contents

1 • CEM-2020

The optional CEM-2020 is a remote auxiliary device that provides additional DGC-2020ES contact inputs and outputs. Two types of modules are available. A low current module (CEM-2020) provides 24 contact outputs and high current module (CEM-2020H) provides 18 contact outputs.

Features

CEM-2020s have the following features:

- 10 Contact Inputs
- 18 Contact Outputs (CEM-2020H) or 24 Contact Outputs (CEM-2020)
- Functionality of Inputs and Outputs assigned by BESTlogic™*Plus* Programmable Logic
- Communications via CAN

Specifications

Control Power

Nominal ..... 12 or 24 Vdc
Range ..... 8 to 32 Vdc (Withstands cranking ride-through down to 6 Vdc for 500 ms)

Maximum Power Dissipation

CEM-2020 ..... 14 W
CEM-2020H ..... 8 W

Contact Inputs

The CEM-2020 contains 10 programmable inputs that accept dry contacts.

Time from a CEM-2020 input application to:

- Shut down the generator via an alarm = 700 ms max
- Close a relay on board the DGC-2020ES = 300 ms max
- Close a relay on board the CEM-2020 = 550 ms max

Notes

A CEM-2020 contact input is true (on) if the input is connected to battery ground with a resistance of less than 200 ohms.

The maximum length of wire that can be accommodated depends on the resistance of the wire, and the resistance of the contacts of the device driving the input at the far end of the wire.

The maximum wire length can be calculated as follows:

L_{max} = (200 – R_{device})/(Resistance per Foot of Desired Wire)

Contact Outputs

Ratings

CEM-2020
Outputs 5 through 16 ..... 1 Adc at 30 Vdc, Form C *
Outputs 17 through 28 ..... 4 Adc at 30 Vdc, Form C – 1.2 A Pilot Duty †

CEM-2020H
Outputs 5 through 16 ..... 2 Adc at 30 Vdc, Form C *
Outputs 17 through 22 ..... 10 Adc at 30 Vdc, Form C – 1.2 A Pilot Duty †

* Gold contacts intended for low voltage signaling to dry circuits. Not rated for inductive loads or pilot duty.

† For pilot duty, the load must be in parallel with a diode rated at least 3 x the coil current and 3 x the coil voltage.

Communications Interface

CAN

Differential Bus Voltage.....1.5 to 3 Vdc
Maximum Voltage .....–32 to +32 Vdc with respect to negative battery terminal
Communication Rate.....250 kb/s

Type Tests

Shock

Withstands 15 G in three perpendicular planes.

Vibration

Swept over the following ranges for12 sweeps in each of three mutually perpendicular planes with each 15-minute sweep consisting of the following:

5 to 29 to 5 Hz.....1.5 G peak for 5 min.
29 to 52 to 29 Hz.....0.036 in (0.914 mm) Double Amplitude for 2.5 min.
52 to 500 to 52 Hz.....5 G peak for 7.5 min.

Ignition System

Tested in close proximity to an unshielded, unsuppressed Altronic DISN 800 ignition system.

HALT (Highly Accelerated Lift Testing)

HALT is used by Basler Electric to prove that our products will provide the user with many years of reliable service. HALT subjects the device to extremes in temperature, shock, and vibration to simulate years of operation, but in a much shorter period span. HALT allows Basler Electric to evaluate all possible design elements that will add to the life of this device. As an example of some of the extreme testing conditions, the CEM-2020 was subjected to temperature tests (tested over a temperature range of –80°C to +130°C), vibration tests (of 5 to 50 G at +25°C), and temperature/vibration tests (tested at 10 to 20 G over a temperature range of –60°C to +100°C). Combined temperature and vibration testing at these extremes proves that the CEM-2020 is expected to provide long-term operation in a rugged environment. Note that the vibration and temperature extremes listed in this paragraph are specific to HALT and do not reflect recommended operation levels. These operational ratings are included in this section.

Environment

Humidity .....Complies with IEC 68-2-38

Temperature
Operating.....–40 to +158°F (–40 to +70°C)
Storage .....–40 to +185°F (–40 to +85°C)

UL Approval (CEM-2020 Only)

The CEM-2020 and CEM-2020H are Recognized Components applicable to the Canadian and US safety standards and requirements by UL. The product is covered under UL File (E97035 FTPM2/FTPM8) and evaluated to the following standards through UL:

- UL6200
- CSA C22.2 No. 14

CE and UKCA Compliance

This product has been evaluated and complies with the relevant essential requirements set forth by the EU legislation and UK Parliament.

- Low Voltage Directive (LVD) - 2014/35/EU
- Electromagnetic Compatibility (EMC) - 2014/30/EU
- Hazardous Substances (ROHS2) -2011/65/EU

Harmonized Standards used for evaluation:

- EN 50178 - *Electronic Equipment for use in Power Installations*
- EN 61000-6-4 - *Electromagnetic Compatibility (EMC), Generic Standards, Emission Standard for Industrial Environments*
- EN 61000-6-2 - *Electromagnetic Compatibility (EMC), Generic Standards, Immunity for Industrial Environments*
- EN 50581 – *Technical Documentation for the Assessment of Electrical and Electric Products with Respect to the Restriction of Hazardous Substances (ROHS2)*

NFPA Compliance

Designed to comply with NFPA Standard 110, *Standard for Emergency and Standby Power*.

Maritime Recognition

American Bureau of Shipping (ABS) – For current certificates, see www.basler.com.

FCC Requirements

This product complies with FCC 47 CFR Part 15.

China RoHS

The following table serves as the declaration of hazardous substances for China in accordance with PRC standard SJ/T 11364-2014. The EFUP (Environment Friendly Use Period) for this product is 40 years.

PRODUCT:	CEM-2020									
零件名称 Part Name	有害物质 Hazardous Substances									
	铅 Lead (Pb)	汞 Mercury (Hg)	镉 Cadmium (Cd)	六价铬 Hexavalent Chromium (Cr^{6+})	多溴联苯 Polybrominated Biphenyls (PBB)	多溴二苯醚 Polybrominated Diphenyl Ethers (PBDE)	邻苯二甲酸二丁酯 Dibutyl Phthalate (DBP)	邻苯二甲酸丁苄酯 Benzyl butyl phthalate (BBP)	邻苯二甲酸二酯 Bis(2-ethylhexyl) phthalate (BEHP)	邻苯二甲酸二异丁酯 Diisobutyl phthalate (DIBP)
金属零件 Metal parts	O	O	O	O	O	O	O	O	O	O
聚合物 Polymers	O	O	O	O	O	O	O	O	O	O
电子产品 Electronics	X	O	X	O	O	O	O	O	O	O
电缆和互连配件 Cables & interconnect accessories	O	O	O	O	O	O	O	O	O	O
绝缘材料 Insulation material	O	O	O	O	O	O	O	O	O	O

本表格依据 SJ/T11364 的规定编制。

O: 表示该有害物质在该部件所有均质材料中的含量均在 GB/T 26572 规定的限量要求以下。

X: 表示该有害物质至少在该部件的某一均质材料中的含量超出 GB/T 26572 规定的限量要求。

This form was prepared according to the provisions of standard SJ/T11364.

O: Indicates that the hazardous substance content in all homogenous materials of this part is below the limit specified in standard GB/T 26252.

X: Indicates that the hazardous substance content in at least one of the homogenous materials of this part exceeds the limit specified in standard GB/T 26572.

Physical

Dimensions.....See *Installation* later in this chapter.

Weight

CEM-2020 .....2.25 lb (1.02 kg)
CEM-2020H .....1.90 lb (0.86 kg)

Functional Description

Contact Inputs

The CEM-2020 provides 10 programmable contact inputs with the same functionality as the contact inputs on the DGC-2020ES. The label text of each contact input is customizable.

Contact Outputs

CEM-2020

The CEM-2020 provides 24 programmable contact outputs with the same functionality as the contact outputs on the DGC-2020ES. Outputs 5 through 16 can carry 1 A. Outputs 17 through 28 can carry 4 A. The label text of each contact output is customizable.

CEM-2020H

The CEM-2020H provides 18 programmable contact outputs with the same functionality as the contact outputs on the DGC-2020ES. Outputs 5 through 16 can carry 2 A. Outputs 17 through 22 can carry 10 A. The label text of each contact output is customizable.

Communications

CAN

A Control Area Network (CAN) is a standard interface that enables communication between the CEM-2020 and the DGC-2020ES.

BESTCOMSPlus® Software

BESTCOMS*Plus* provides the user with a point-and-click means to set and monitor the Contact Expansion Module. Installation and operation of BESTCOMS*Plus* is described in the BESTCOMS*Plus* chapter.

Installation

Contact Expansion Modules are delivered in sturdy cartons to prevent shipping damage. Upon receipt of a module, check the part number against the requisition and packing list for agreement. Inspect for damage, and if there is evidence of such, immediately file a claim with the carrier and notify the Basler Electric regional sales office or your sales representative.

If the device is not installed immediately, store it in the original shipping package in a moisture- and dust-free environment.

Mounting

Contact Expansion Modules are contained in a potted plastic case and may be mounted in any convenient position. The construction of a Contact Expansion Module is durable enough to mount directly on a genset using ¼-inch hardware. Hardware selection should be based on any expected shipping/transportation and operating conditions. The torque applied to the mounting hardware should not exceed 65 in-lb (7.34 N•m).

See Figure 1-1 for CEM-2020 overall dimensions. All dimensions are shown in inches with millimeters in brackets.

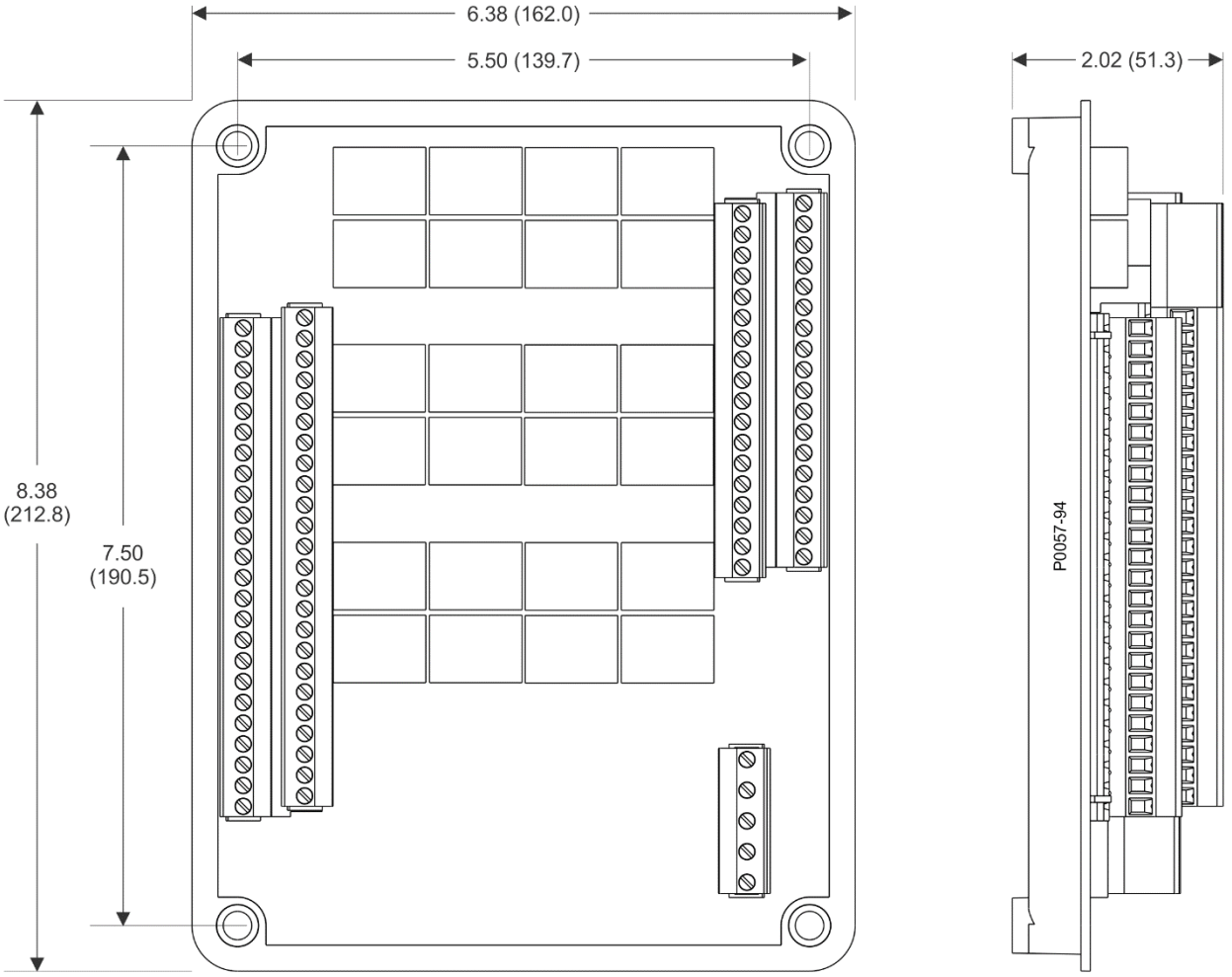

Figure 1-1. CEM-2020 Overall Dimensions

See Figure 1-2 for CEM-2020H overall dimensions. All dimensions are shown in inches with millimeters in brackets.

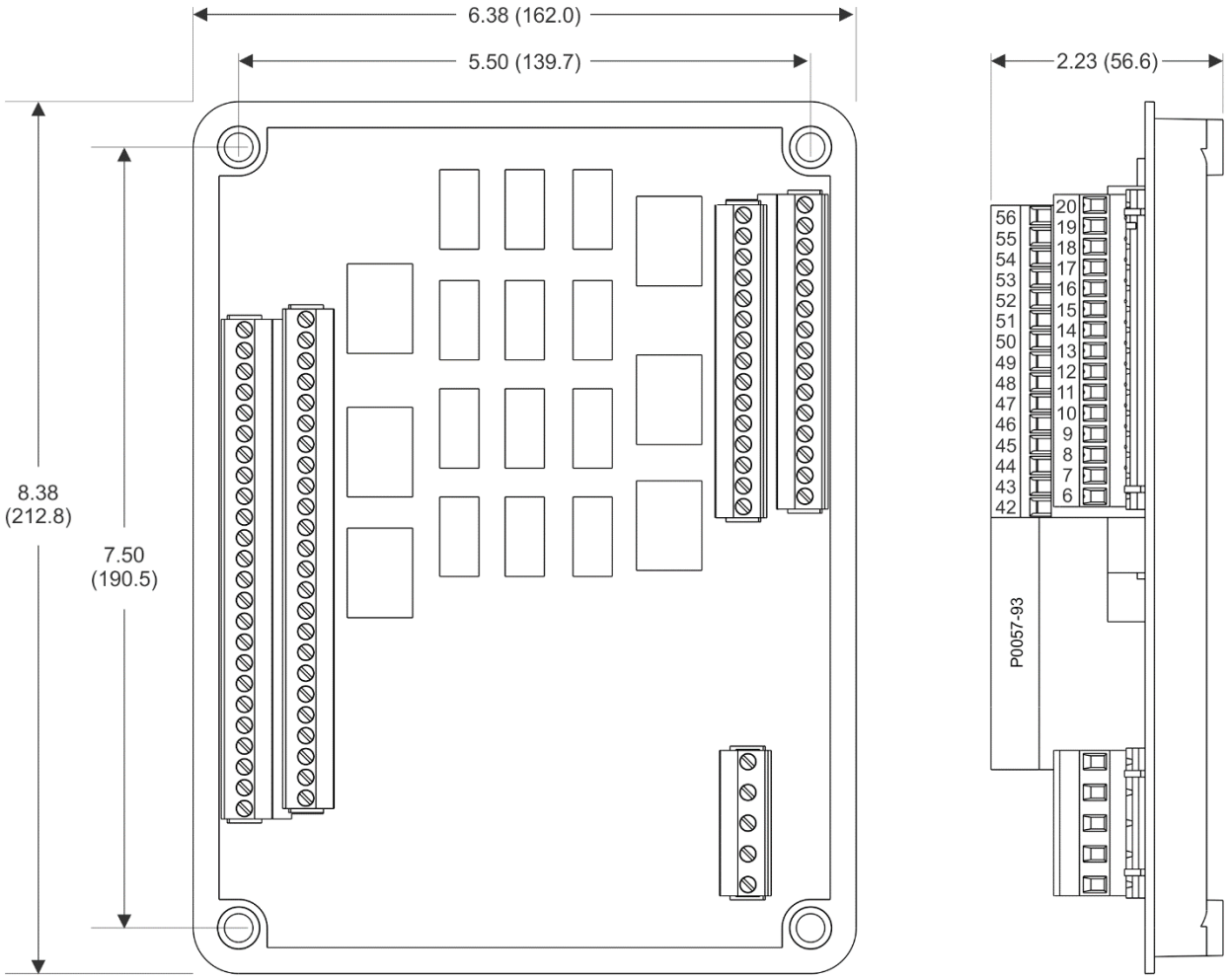

Figure 1-2. CEM-2020H Overall Dimensions

Connections

Contact Expansion Module connections are dependent on the application. Incorrect wiring may result in damage to the module.

Note

Control power from the battery must be of the correct polarity. Although reverse polarity will not cause damage, the CEM-2020 will not operate.

Be sure that the CEM-2020 is hard-wired to earth ground with no smaller than 12 AWG copper wire attached to the chassis ground terminal on the module.

It is recommended to minimize the vibration load on the connector plug by ensuring that wires are well-constrained, with no more than 6 to 8 inches of unconstrained wire length near the connector plugs.

Terminations

The terminal interface consists of plug-in connectors with screw-down compression terminals.

CEM-2020 connections are made with one 5-position connector, two 18-position connectors, and two 24-position connectors with screw-down compression terminals. These connectors plug into headers on the

CEM-2020. The connectors and headers have dovetailed edges that ensure proper connector orientation. The connectors and headers are uniquely keyed to ensure that the connectors mate only with the correct headers. Connector screw terminals accept a maximum wire size of 12 AWG (3.31 mm^2). Maximum screw torque is 5 inch-pounds (0.56 N•m).

Control Power

The Contact Expansion Module control power input accepts either 12 Vdc or 24 Vdc and tolerates voltage over the range of 6 to 32 Vdc. Control power must be of the correct polarity. Although reverse polarity will not cause damage, the CEM-2020 will not operate. Control power terminals are listed in Table 1-1.

It is recommended that a fuse be added for additional protection for the wiring to the battery input of the Contact Expansion Module. A Bussmann ABC-7 fuse or equivalent is recommended.

Table 1-1. Control Power Terminals

Terminal	Description
P1- ⏚ (SHIELD)	Chassis ground connection
P1- – (BATT–)	Negative side of control power input
P1 + (BATT+)	Positive side of control power input

Contact Inputs and Contact Outputs

The CEM-2020 (Figure 1-3) has 10 contact inputs and 24 contact outputs. The CEM-2020H (Figure 1-4) has 10 contact inputs and 18 contact outputs.

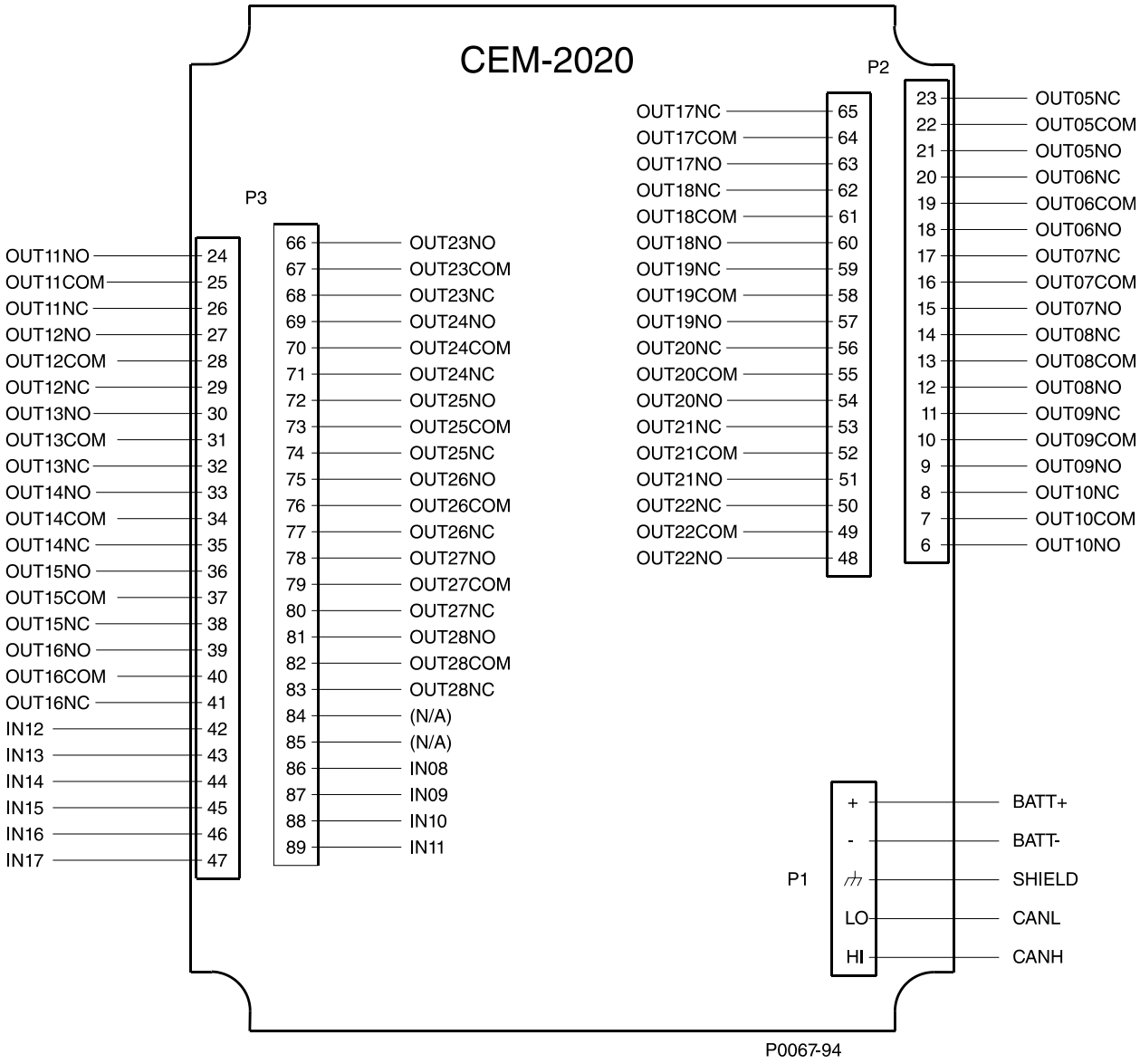

Figure 1-3. CEM-2020 Contact Input and Contact Output Terminals

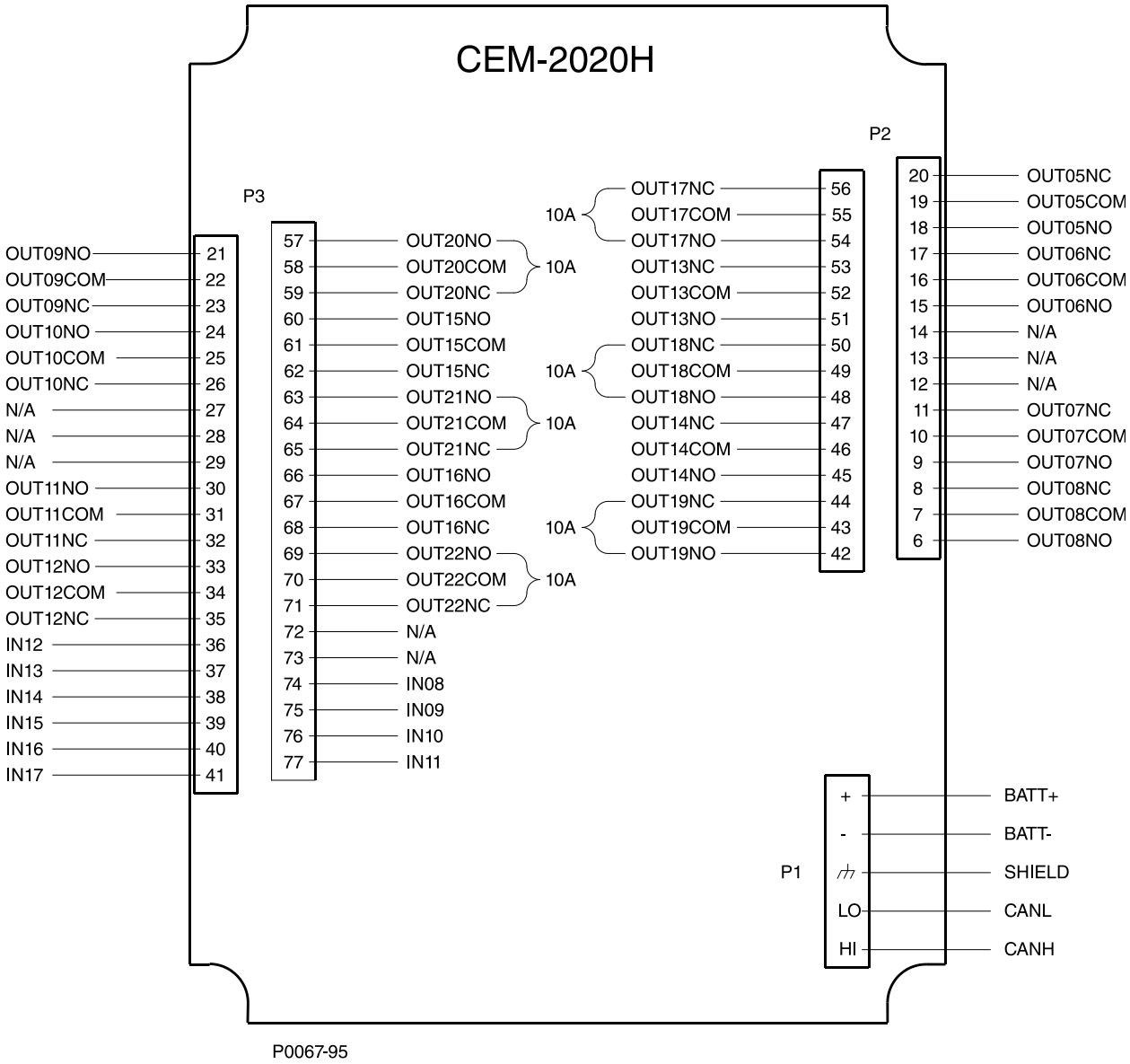

Figure 1-4. CEM-2020H Contact Input and Contact Output Terminals

CAN Interface

These terminals provide communication using the SAE J1939 protocol and provide high-speed communication between the Contact Expansion Module and the DGC-2020ES. Connections between the CEM-2020 and DGC-2020ES should be made with twisted-pair, shielded cable. CAN interface terminals are listed in Table 1-2. Refer to Figure 1-5 and Figure 1-6.

Table 1-2. CAN Interface Terminals

Terminal	Description
P1- HI (CAN H)	CAN high connection (yellow wire)
P1- LO (CAN L)	CAN low connection (green wire)
P1- ⏚ (SHIELD)	CAN drain connection

Notes

1. If the CEM-2020 is providing one end of the J1939 bus, a 120 ohm, ½ watt terminating resistor should be installed across terminals P1- LO (CANL) and P1- HI (CANH).
2. If the CEM-2020 is not part of the J1939 bus, the stub connecting the CEM-2020 to the bus should not exceed 914 mm (3 ft) in length.
3. The maximum bus length, not including stubs, is 40 m (131 ft).
4. The J1939 drain (shield) should be grounded at one point only. If grounded elsewhere, do not connect the drain to the CEM-2020.

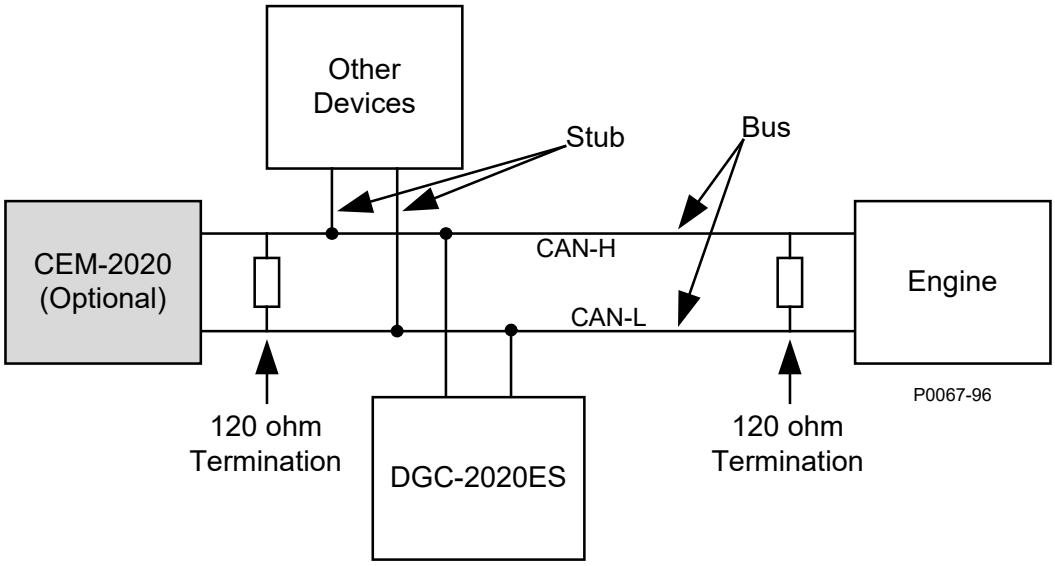

Figure 1-5. CAN Interface with CEM-2020 providing One End of the Bus

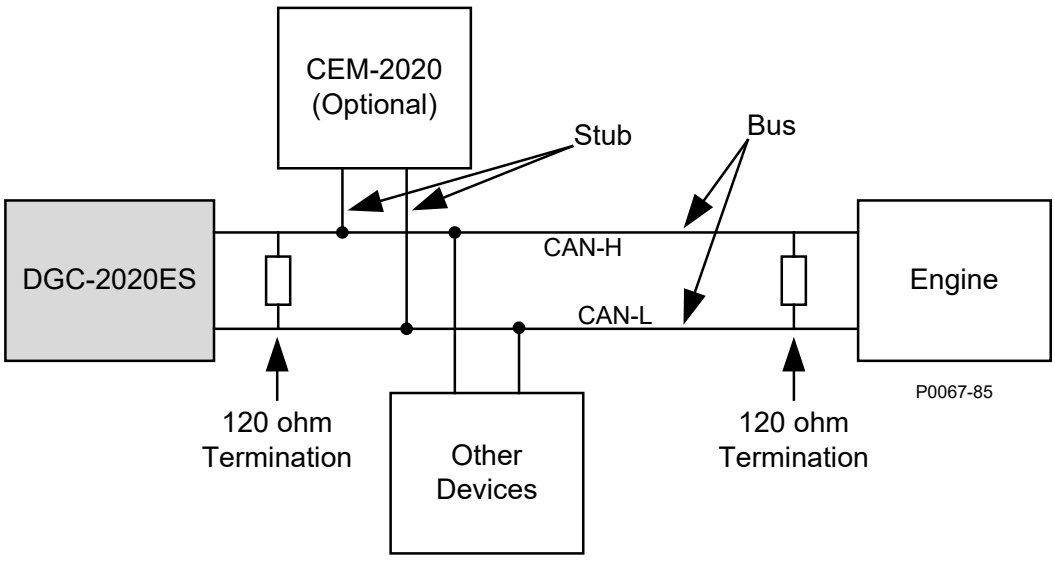

Figure 1-6. CAN Interface with DGC-2020ES providing One End of the Bus

Remote Contact Input Configuration

The CEM-2020 provides 10 contact inputs. Each of the 10 contact inputs can be independently configured to annunciate an alarm or pre-alarm when the input senses a contact closure. A user-adjustable time delay can be set to delay recognition of a contact input. By default, all inputs are configured so that they do not trigger an alarm or pre-alarm.

To make identifying the contact inputs easier, a user-assigned name can be given to each input.

Contacts can be recognized always or only while the engine is running.

The remote contact inputs are incorporated into a BESTlogic*Plus* programmable logic scheme by selecting them from the *I/O* group in BESTlogic*Plus*. For more details, refer to the BESTlogic*Plus* chapter in the *Configuration* manual.

Remote contact input status is available in BESTlogic*Plus* Programmable Logic when “None” is selected for Alarm Configuration.

The *Remote Contact Input*s screen is found in the BESTCOMS*Plus Settings Explorer* under the *Programmable Inputs* category. If using the front panel, navigate to Settings > Programmable Inputs > Configurable Inputs. The BESTCOMS*Plus* Remote Contact Inputs screen is illustrated in Figure 1-7.

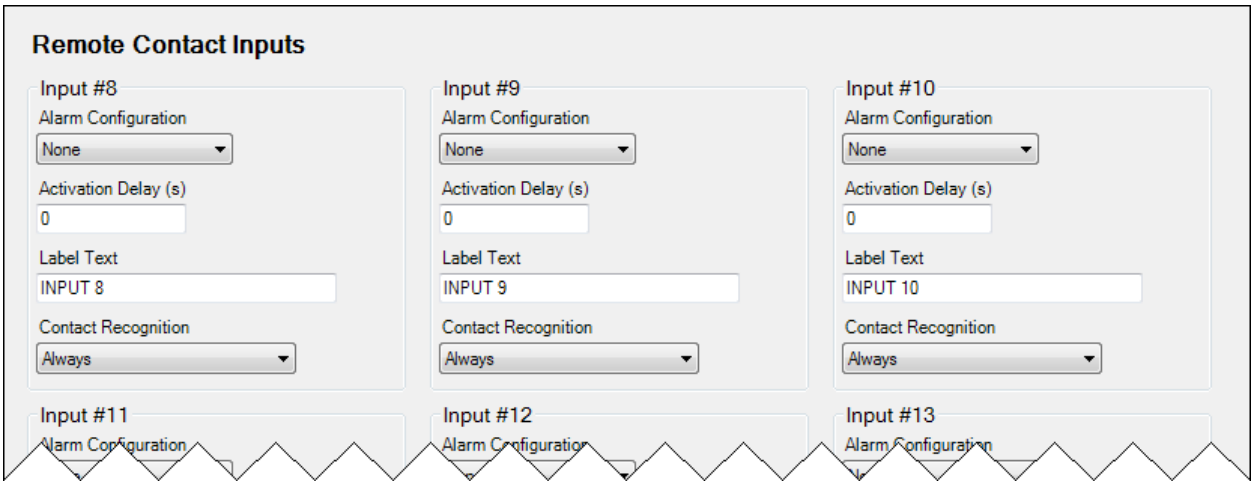

Figure 1-7. Settings Explorer, Programmable Inputs, Remote Contact Inputs Screen

Remote Contact Output Configuration

To make identifying the contact outputs easier, each of the contact outputs can be given a user-assigned name.

The contact outputs are incorporated into a BESTlogic*Plus* programmable logic scheme by selecting them from the *I/O* group in BESTlogic*Plus*. For more details, refer to the BESTlogic*Plus* chapter in the *Configuration* manual.

The *Remote Contact Output*s screen is found in the BESTCOMS*Plus Settings Explorer* under the *Programmable Inputs* category. If using the front panel, navigate to Settings > Programmable Outputs > Configurable Outputs. The BESTCOMS*Plus* Contact Outputs screen is illustrated in Figure 1-8.

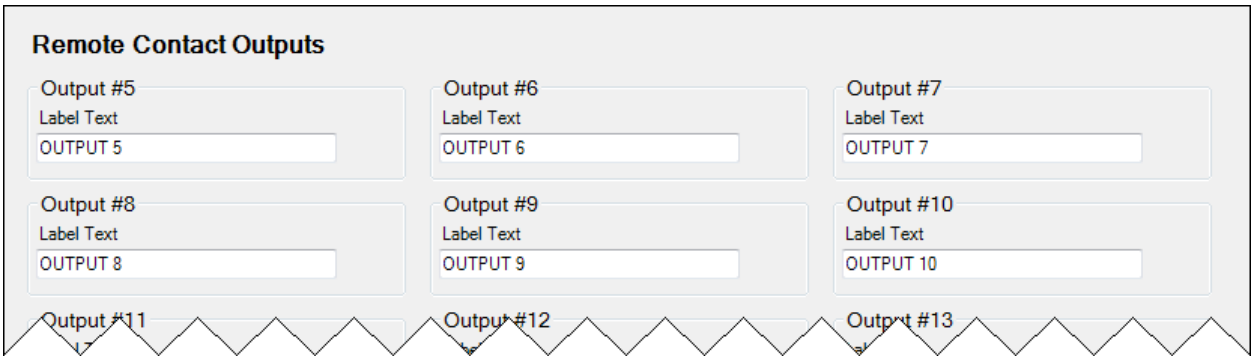

Figure 1-8. Settings Explorer, Programmable Outputs, Remote Contact Outputs Screen

Firmware Updates

Refer to the *Device Information* chapter in the *Configuration* manual for information on upgrading firmware in the CEM-2020.

Repair

Contact Expansion Modules are manufactured using state-of-the-art surface-mount technology. As such, Basler Electric recommends that no repair procedures be attempted by anyone other than Basler Electric personnel.

Before returning the CEM-2020 for repair, contact Basler Electric Technical Services Department at 618-654-2341 for a return authorization number.

Maintenance

Preventive maintenance consists of periodically checking that the connections between the CEM-2020 and the system are clean and tight.

Storage

This device contains long-life aluminum electrolytic capacitors. For devices that are not in service (spares in storage), the life of these capacitors can be maximized by energizing the device for 30 minutes once per year.

2 • Troubleshooting

If you do not get the results that you expect from the DGC-2020ES, first check the programmable settings for the appropriate function. Use the following troubleshooting procedures when difficulties are encountered in the operation of your genset control system.

Communications

USB Port Does Not Operate Properly

Step 1. Verify that the proper port of your computer is being used. For more information, refer to the *Communication* chapter in the *Configuration* manual.

CAN Communication Does Not Operate Properly

Step 1: Verify that there is a 120-ohm termination resistor on each end of the bus section of the wiring, and that there are not any termination resistors at any node connections that are on stubs from the main bus.

Step 2: Check all CAN wiring for loose connections and verify that the CAN H and CAN L wires have not gotten switched somewhere on the network.

Step 3: Verify that the cable length of the bus section of the wiring does not exceed 40 meters (131 feet), and verify that any stubs from the main bus do not exceed 3 meters (9.8 feet) in length.

Step 4: If the engine is equipped with a Volvo or mtu ECU, verify that the ECU Configuration setting is set to match the actual ECU configuration.

Inputs and Outputs

Programmable Inputs Do Not Operate as Expected

Step 1. Verify that all wiring is properly connected. Refer to the *Typical Connections* chapter in the *Installation* manual.

Step 2. Confirm that the inputs are programmed properly.

Step 3. Ensure that the input at the DGC-2020ES is actually connected to the BATT– terminal (17).

Programmable Outputs Do Not Operate as Expected

Step 1. Verify that all wiring is properly connected. Refer to the *Typical Connections* chapter in the *Installation* manual.

Step 2. Confirm that the outputs are programmed properly.

Metering/Display

Incorrect Display of Battery Voltage, Coolant Temperature, Oil Pressure, or Fuel Level

Step 1. Verify that all wiring is properly connected. Refer to the *Typical Connections* chapter in the *Installation* manual.

Step 2. Confirm that the SENDER COM terminal (2) is connected to the negative battery terminal and the engine-block side of the senders. Current from other devices sharing this connection can cause erroneous readings.

Step 3. If the displayed battery voltage is incorrect, ensure that the proper voltage is present between the BATT+ terminal (18) and the SENDER COM terminal (2).

Step 4. Verify that the correct senders are being used.

Step 5. Use a voltmeter connected between the BATT– terminal (17) and the SENDER COM terminal (2) on the DGC-2020ES to verify that there is no voltage difference at any time. Any voltage differences may manifest themselves as erratic sender readings. Wiring should be corrected so that no differences exist.

Step 6: Check the sender wiring and isolate sender wiring from any of the ac wiring in the system. The sender wiring should be located away from any power ac wiring from the generator and any ignition wiring. Separate conduits should be used for sender wiring and any ac wiring.

Incorrect Display of Generator Voltage

Step 1. Verify that all wiring is properly connected. Refer to the *Typical Connections* chapter in the *Installation* manual.

Step 2. Ensure that the proper voltage is present at the DGC-2020ES voltage sensing inputs (40, 41, 43, and 45).

Step 3. Verify that the voltage transformer ratio and sensing configuration is correct.

Step 4. Confirm that the voltage sensing transformers are correct and properly installed.

Incorrect Measurement or Display of Generator Current

Step 1. Verify that all wiring is properly connected. Refer to the *Typical Connections* chapter in the *Installation* manual.

Step 2. Ensure that the proper current is present at the DGC-2020ES current sensing inputs 33, 34, 35, 36, 37, and 38.

Step 3. Verify that the current sensing transformer ratios are correct.

Step 4. Confirm that the current sensing transformers are correct and properly installed.

Incorrect Display of Engine RPM

Step 1. Verify that all wiring is properly connected. Refer to the *Typical Connections* chapter in the *Installation* manual.

Step 2. Verify that the flywheel teeth setting is correct.

Step 3. Verify that the prime mover governor is operating properly.

Step 4. Verify that the measured frequency of the voltage at the MPU input (31 and 32) is correct.

Step 5. If the MPU is shared with the governor, verify that the polarity of the MPU input to the governor matches the polarity of the MPU input to the DGC-2020ES.

DGC-2020ES Indicates Incorrect Power Factor

Check the rotation of the machine and the labeling of the A-B-C terminals. The machine must be rotating in the same phase sequence as dictated by the generator phase rotation setting for correct power factor metering. A power factor indication of 0.5 with resistive load present is a symptom of incorrect phase rotation.

LCD is Blank and all LEDs are Flashing at Approximately Two-Second Intervals

This indicates that the DGC-2020ES does not detect that valid application firmware is installed. The unit is running its boot loader program, waiting to accept a firmware upload.

Step 1. Start BESTCOMS*Plus*®. Use the top pull-down menu and select FILE > NEW > DGC-2020ES.

Step 2. Select COMMUNICATIONS > UPLOAD DEVICE FILES and select the device package file that contains the firmware and language you want to upload.

Step 3. Check the boxes for DGC-2020ES Firmware and DGC-2020ES Language Module. Click the UPLOAD button to start the upload process.

Ground Faults Detected in Ungrounded System Applications

Step 1: Verify that there is no connection from the neutral connection of the generator to the system ground.

Step 2: Perform insulation resistance tests on the system wiring to check for insulation integrity in the overall system.

Step 3: If ground faults are detected on a DGC-2020ES in an ungrounded system application, it is recommended that potential transformers be employed on the voltage sensing inputs to provide full isolation between the DGC-2020ES and monitored voltage phases.

Step 4: If potential transformers are in place, remove the connectors from the DGC-2020ES one at a time. If removal of a connector removes the ground fault, check the system wiring to that connector and out into the system to verify that connections are secure and all wiring insulation is in good condition.

Generator Breaker and Mains Breaker

Generator Breaker Will Not Close to a Dead Bus

Step 1: Review the description of how the generator breaker logic element functions contained in the GENBRK logic element description in the BESTlogic™*Plus* chapter in the *Configuration* manual.

Step 2: Review the section on breaker close requests in the *Breaker Management* chapter in the *Configuration* manual.

Step 3: Navigate to the SETTINGS > BREAKER MANAGEMENT > BREAKER HARDWARE > GEN BREAKER screen and set DEAD BUS CL ENBL to ENABLE.

Step 4: Verify that the Generator status is stable. The breaker will not close if the generator status is not stable. Check status by using the Metering Explorer in BESTCOMS*Plus* and verify that when the generator is running, the GEN STABLE status LED is lit. If necessary, modify the settings on the SETTINGS > BREAKER MANAGEMENT > BUS CONDITION DETECTION screen.

Step 5: Verify the bus status is DEAD. Check status by using the Metering Explorer in BESTCOMS*Plus* and verify that when the generator is running, the BUS DEAD status LED is lit. If necessary, modify the settings on the SETTINGS > BREAKER MANAGEMENT > BUS CONDITION DETECTION screen.

Step 6: Verify the connections in BESTlogic*Plus* Programmable Logic to the generator breaker logic element. The *Status* input must be driven by an “A” or normally open contact from the generator breaker. The OPEN and CLOSE command inputs on the left side of the logic block are inputs for open and close commands. These can be wired to physical inputs if it is desired to have open and close command switches. If they are wired, they must either be pulsed inputs, or some logic must be employed so that the open and close command inputs are never driven at the same time. If these are both driven at the same time, the breaker is receiving open and close commands simultaneously. The breaker will not change state if it is being commanded to open and close at the same time.

Step 7: Verify the breaker is receiving a close command. Breaker close command sources are:

- The DGC-2020ES itself when the automatic mains fail transfer (ATS) feature is enabled.
- The DGC-2020ES itself when the RUN WITH LOAD logic element receives a *Start* pulse in the programmable logic.
- The DGC-2020ES itself when started from the Exercise Timer and the Run with Load box is checked in the Generator Exerciser settings.
- Manual Breaker Close Input Contacts applied to the Open and Close inputs on the left side of the Generator Breaker logic element in the programmable logic.

Step 8: Verify the wiring to the breaker from the DGC-2020ES. If it seems OK, you can do a manual close and open by modifying the programmable logic. Map some unused outputs to the OPEN and CLOSE outputs from the Gen Breaker Block in the programmable logic. Map a virtual switch to the logic output that would normally be the breaker open output. Map another virtual switch to the logic output that would normally be the breaker close output. Connect with BESTCOMS*Plus*, and exercise the virtual switches using the Control panel located in the Metering Explorer. Never turn open and close on at the same time. This could damage the breaker and/or motor operator. If everything is working as expected, restore the logic to its original diagram.

Generator Breaker Does Not Open When It Should

Step 1: Review the description of how the generator breaker logic element functions contained in the GENBRK logic element description in the *BESTlogicPlus* chapter in the *Configuration* manual.

Step 2: Review the section on breaker operation requests in the *Breaker Management* chapter in the *Configuration* manual.

Step 3: Verify the connections in BESTlogic*Plus* Programmable Logic to the generator breaker logic element. The *Status* input must be driven by an “A” or normally open contact from the generator breaker. The OPEN and CLOSE command inputs on the left side of the logic block are inputs for open and close commands. These can be wired to physical inputs if it is desired to have open and close command switches. If they are wired, they must either be pulsed inputs, or some logic must be employed so that the open and close command inputs are never driven at the same time. If these are both driven at the same time, the breaker is receiving open and close commands simultaneously. The breaker will not change state if it is being commanded to open and close at the same time.

Step 4: Verify the breaker is receiving an open command. Breaker open command sources are:

- The DGC-2020ES itself when the automatic transfer (ATS) feature is enabled.
- The DGC-2020ES itself when the RUN WITH LOAD logic element receives a *Stop* pulse in the programmable logic.
- The DGC-2020ES itself when shutting down the engine due to an active alarm.
- The DGC-2020ES itself when ending a run session from the Exercise Timer and the *Run with Load* box is checked in the Generator Exerciser settings.
- Manual Breaker Open Input Contacts applied to the Open and Close inputs on the left side of the Generator Breaker logic element in the programmable logic.

Step 5: Verify the wiring to the breaker from the DGC-2020ES. If it seems OK, you can do a manual close and open by modifying the programmable logic. Map some unused outputs to the OPEN and CLOSE outputs from the Gen Breaker Block in the programmable logic. Map a virtual switch to the logic output that would normally be the breaker open output. Map another virtual switch to the logic output that would normally be the breaker close output. Connect with BESTCOMS*Plus*, and exercise the virtual switches using the Control panel located in the Metering Explorer. Never turn open and close on at the same time. This could damage the breaker and/or motor operator. If everything is working as expected, restore the logic to its original diagram.

Mains Breaker Does Not Open When Mains Fails

Step 1: Verify that a Mains Breaker has been configured by examining the settings on the SETTINGS > BREAKER MANAGEMENT > BREAKER HARDWARE screen.

Step 2: Verify the mains breaker has been correctly included in the programmable logic.

Step 3: Verify that the MAINS FAIL TRANSFER parameter is set to ENABLE on the SETTINGS > BREAKER MANAGEMENT > BREAKER HARDWARE screen.

Step 4: Verify that a failure of the mains is detected by the DGC-2020ES. Check status using the Metering Explorer in BESTCOMS*Plus* and verify that the MAINS FAIL status LED is lit when

the power on the DGC-2020ES bus voltage input is either out of voltage or frequency range. If necessary, modify the settings on the SETTINGS > BREAKER MANAGEMENT > BUS CONDITION DETECTION screen to achieve correct detection.

Step 5: Verify the wiring to the breaker from the DGC-2020ES. If it seems OK, you can do a manual close and open by modifying the programmable logic. Map some unused outputs to the OPEN and CLOSE outputs from the Gen Breaker Block in the programmable logic. Map a virtual switch to the logic output that would normally be the breaker close output. Map another virtual switch to the logic output that would normally be the breaker close output. Connect with BESTCOMS*Plus*, and exercise the virtual switches using the Control panel located in the Metering Explorer. Never turn open and close on at the same time. This could damage the breaker and/or motor operator. If everything is working as expected, restore the logic to its original diagram.

Mains Breaker Does Not Close After Mains Returns

Step 1: Verify that a Mains Breaker has been configured by examining the settings on the SETTINGS > BREAKER MANAGEMENT > BREAKER HARDWARE screen.

Step 2: Verify the mains breaker has been correctly included in the programmable logic.

Step 3: Verify that the MAINS FAIL TRANSFER parameter is set to ENABLE on the SETTINGS > BREAKER MANAGEMENT > BREAKER HARDWARE screen.

Step 4: Verify that stable mains power is detected by the DGC-2020ES. Check status using the Metering Explorer in BESTCOMS*Plus* and verify that the MAINS STABLE status LED is lit when the power on the DGC-2020ES bus voltage input is good. If necessary, modify the settings on the SETTINGS > BREAKER MANAGEMENT > BUS CONDITION DETECTION screen to achieve correct detection.

Step 5: Verify the wiring to the breaker from the DGC-2020ES. If it seems OK, you can do a manual close and open by modifying the programmable logic. Map some unused outputs to the OPEN and CLOSE outputs from the Gen Breaker Block in the programmable logic. Map a virtual switch to the logic output that would normally be the breaker open output. Map another virtual switch to the logic output that would normally be the breaker close output. Connect with BESTCOMS*Plus*, and exercise the virtual switches using the Control panel located in the Metering Explorer. Never turn open and close on at the same time. This could damage the breaker and/or motor operator. If everything is working as expected, restore the logic to its original diagram.

DGC-2020ES Front Panel Debug Screen

There is one debug screen in the DGC-2020ES that can be useful for debugging I/O module related issues. The following debug screen is available: CEM DEBUG

CEM DEBUG

This screen shows the binary data that is being sent between the CEM-2020 (Contact Expansion Module) and the DGC-2020ES.

The CEM DEBUG screen is located on the front panel at SETTINGS > SYSTEM PARAMS > REMOTE MODULE SETUP > CEM SETUP > CEM DEBUG MENU.

The following parameters are visible on the CEM DEBUG screen:

- DGC TO CEM BP: DGC-2020ES to CEM-2020 Binary Points. This is the status of the CEM-2020 output relays being transmitted from the DGC-2020ES to the CEM-2020. This is a 32-bit, bit packed number representing the desired states of the CEM-2020 outputs. The left most bit is the first output, etc.
- CEM TO DGC BP: CEM-2020 to DGC-2020ES Binary Points. This is the status of the CEM-2020 inputs being transmitted from the CEM-2020 to the DGC-2020ES. This is a 32-bit, bit packed number representing the metered states of the CEM-2020 inputs. The left most bit is the first input, etc.

www.basler.com

Highland, Illinois USA
Tel: +1 618.654.2341
Fax: +1 618.654.2351
email: info@basler.com

Suzhou, P.R. China
Tel: +86 512.8227.2888
Fax: +86 512.8227.2887
email: chinainfo@basler.com